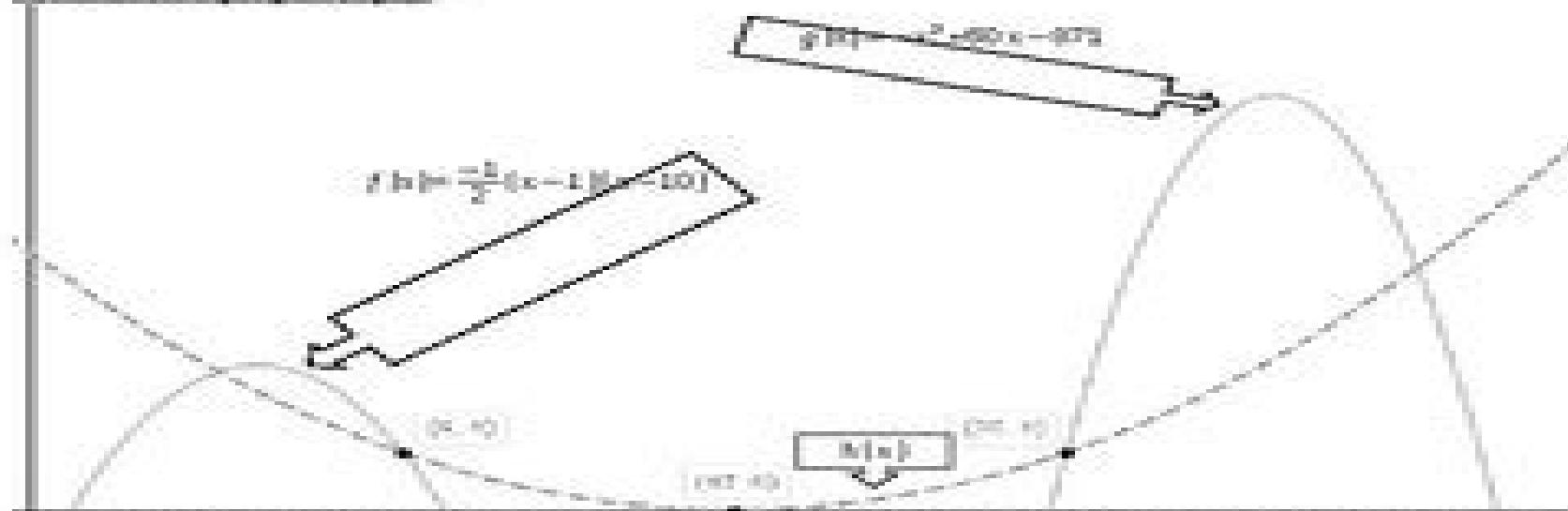


Part 1 - Bridging the gap



- Pictured above are the two existing equations for the uphill portions of the roller coaster, $f(x)$ and $g(x)$. The materials for these portions has already been ordered, so you cannot adjust them. Instead, the owners of the park are asking for the equation of a downhill portion that will bridge the gap between them. Using the information above, write an equation with a minimum point of $(7, -4)$, that intersects $f(x)$ at $(9, 0)$ and intersects $g(x)$ at $(15, 0)$.
- Write this equation in both vertex and standard form.
- Show all of your work below.

Quadratic Performance Task

Huangqi Zhang

A red circular graphic with a gradient, appearing as a semi-circle or a stylized arrow pointing to the right, located to the right of the author's name.

Quadratic Performance Task:

Parallel Curriculum Units for Mathematics, Grades 6–12 Jann H. Leppien, Jeanne H. Purcell, 2011-04-07 Maximize your mathematics curriculum with this powerful guidebook that shows how to create a high quality curriculum and differentiate lessons to benefit all students

A Collection of Performance Tasks & Rubrics: High School

Mathematics Charlotte Danielson, Elizabeth Marquez, 2014-05-22 This book provides a collection of performance tasks and scoring rubrics for a number of important topics in high school mathematics Included are many samples of student work which clarify the tasks and anchor the points of the scoring rubrics Clarity for Learning John Almarode, Kara

Vandas, 2018-10-24 AN ESSENTIAL RESOURCE FOR STUDENT AND TEACHER CLARITY With the ever changing landscape of education teachers and leaders often find themselves searching for clarity in a sea of standards curriculum resources and competing priorities Clarity for Learning offers a simple and doable approach to developing clarity and sharing it with students Are both teachers and students clear about what must be learned why students are learning it and how they can be successful Are students able to determine their next steps in learning through quality feedback and assessment Have teachers had the time and support to collaborate around clarity to ensure an aligned approach within your school system This book offers five powerful practices that include Gaining clarity Sharing clarity Feedback with clarity Assessing with clarity Collaborating with clarity In addition the book is chock full of examples from teachers and leaders across North America who have shared their journey struggles and successes to provide examples exemplars and models for readers to use to propel their own work forward This is a don't miss resource **Performance Tasks for Operator-skills Research** Richard G. Pearson, 1966

Captivate, Activate, and Invigorate the Student Brain in Science and Math, Grades 6-12 John Almarode, Ann M. Miller, 2013-04-02 Banish boredom once and for all If your STEM lessons are falling on disinterested ears it's time to mix things up What you need are more engaging brain based science and math strategies to captivate your students attention activate their prior knowledge and invigorate their interest Blending current research on the student brain with practical methods for teaching science and math John Almarode and Ann M Miller identify six essential ingredients in a recipe for student success In their book you'll discover A customizable framework you can use right away Classroom ready content specific attention grabbers Overt and covert strategies to boost behavioral emotional and cognitive engagement Techniques for making relevant connections that maximize retention With this new approach to captivating STEM lessons you'll energize classroom time and keep your students on task and engaged every day This book links a wealth of best practices in lesson design to the latest research on how the brain learns new information Edward C Nolan PreK 12 Content Specialist Mathematics Montgomery County Public Schools Rockville MD This book is a must read for teachers of math or science who want to increase student achievement and create meaningful learning experiences Melissa Miller Science Instructor Lynch Middle School Farmington AR *Spacecraft Maneuver with Performance Guaranteed* Yufeng Gao, Dongyu

Li,2023-10-21 Facing future oriented aerospace applications large scale space construction and on orbit services have rapidly developed In such emerging and increasingly complex spacecraft maneuvering and control tasks more precise control accuracy and higher performance guarantees need to be fully considered due to the need for safe close rendezvous movements This book is dedicated to solving the aerospace system s performance guaranteed and precise control challenges with the expected transient and strict steady state constraints It is designed so that the aerospace closed loop system can theoretically meet the pre defined or prescribed performance requirements with the simple parameter selection Furthermore the expected performance constraints or indicators of the aerospace system time domain performance response such as settling time overshoot steady state error and state amplitude will be directly guaranteed in the control design Moreover this book systematically proposes a series of spacecraft performance guaranteed control algorithms based on the practical situation of the aerospace system For individual spacecraft control algorithms that consider practical problems such as control task requirements settling time constraints transient performance normalization input command constraints and optimization faced by the on orbit spacecraft are proposed to achieve the precise control objectives of the system under constraints and various complex situations For the pre combination and post combination control of multiple spacecraft game algorithms based on performance guarantees are proposed and thoroughly discussed For spacecraft formations control algorithms that consider full state constraints nonlinear uncertainties output feedback and collision avoidance are proposed This book provides the theoretical basis and simulation experience for scholars and engineers to develop high performance high precision spacecraft control algorithms Furthermore it hopes that these will contribute to the development of the world s aerospace technology **Proceedings** ,1966 *Applications of Human Performance Models to System Design* Grant R. McMillan,David Beevis,Eduardo Salas,2013-06-29 The human factors profession is currently attempting to take a more proactive role in the design of man machine systems than has been character istic of its past Realizing that human engineering contributions are needed well before the experimental evaluation of prototypes or operational systems there is a concerted effort to develop tools that predict how humans will interact with proposed designs This volume provides an over view of one category of such tools mathematical models of human performance It represents a collection of invited papers from a 1988 NATO Workshop The Workshop was conceived and organized by NATO Research Study Group 9 RSG 9 on Modelling of Human Operator Behaviour in Weapon Systems It represented the culmination of over five years of effort and was attended by 139 persons from Europe Canada and the United States RSG 9 was established in 1982 by Panel 8 of the Defence Research Group to accomplish the following objectives Determine the utility and state of the art of human performance modelling Encourage international research and the exchange of ideas Foster the practical application of modelling research Provide a bridge between the models and approaches adopted by engineers and behavioral scientists Present the findings in an international symposium Control of Variable-Geometry Vehicle Suspensions Balázs

Németh,Péter Gáspár,2023-07-08 This book provides a thorough and fresh treatment of the control of innovative variable geometry vehicle suspension systems A deep survey on the topic which covers the varying types of existing variable geometry suspension solutions introduces the study The book discusses three important aspects of the subject robust control design nonlinear system analysis and integration of learning and control methods The importance of variable geometry suspensions and the effectiveness of design methods implemented in the autonomous functionalities of electric vehicles functionalities like independent steering and torque vectoring are illustrated The authors detail the theoretical background of modeling control design and analysis for each functionality The theoretical results achieved through simulation examples and hardware in the loop scenarios are confirmed The book highlights emerging ideas of applying machine learning based methods in the control system with guarantees on safety performance The authors propose novel control methods based on the theory of robust linear parameter varying systems with examples for various suspension systems Academic researchers interested in automotive systems and their counterparts involved in industrial research and development will find much to interest them in the eleven chapters of Control of Variable Geometry Vehicle Suspensions **NASA-University Conference on Manual Control** ,1966 **Deep Reinforcement Learning with Guaranteed Performance** Yinyan Zhang,Shuai Li,Xuefeng Zhou,2019-11-09 This book discusses methods and algorithms for the near optimal adaptive control of nonlinear systems including the corresponding theoretical analysis and simulative examples and presents two innovative methods for the redundancy resolution of redundant manipulators with consideration of parameter uncertainty and periodic disturbances It also reports on a series of systematic investigations on a near optimal adaptive control method based on the Taylor expansion neural networks estimator design approaches and the idea of sliding mode control focusing on the tracking control problem of nonlinear systems under different scenarios The book culminates with a presentation of two new redundancy resolution methods one addresses adaptive kinematic control of redundant manipulators and the other centers on the effect of periodic input disturbance on redundancy resolution Each self contained chapter is clearly written making the book accessible to graduate students as well as academic and industrial researchers in the fields of adaptive and optimal control robotics and dynamic neural networks **Can't Get You Out of My Head: Brain-Body Interactions in Perseverative Cognition** Cristina Ottaviani,Julian F. Thayer,Bart Verkuil,Hugo D. Critchley,Jos F. Brosschot,2018-02-16 Perseverative cognition is defined as the repetitive or sustained activation of cognitive representations of past stressful events or feared events in the future and even at non clinical levels it causes a fight or flight action tendency followed by a cascade of biological events starting in the brain and ending as peripheral stress responses In the past decade such persistent physiological activation has proven to impact individuals health potentially leading to somatic disease As such perseverative cognition has recently been proposed as the missing piece in the relationships between stress psychopathology and risk for health Perseverative cognition is indeed a hallmark of conditions such as anxiety and mood disorders that are at increased

though still unexplained cardiovascular risk Although the pivotal role of ruminative and worrisome thoughts in determining the onset and maintenance of psychopathological disorders has been acknowledged for a long time its effects on the body via reciprocal influences between mental processes and the body's physiology have been neglected Moreover perseverative cognition is definitely not restricted to psychopathology it is extremely common and likely even omnipresent pervading daily life The objective of the Research Topic is to provide an interdisciplinary examination of cutting edge neuroscientific research on brain body signatures of perseverative cognition in both healthy and psychopathological individuals Despite the evident role of the brain in repetitive thinking and the assumption that our mind is embodied brain body pathways from perseverative cognition to health risk have remained largely unexplored

The Boys' Algebra, Including Quadratic Equations; with an Appendix ... James Cahill (Writer on Mathematics.), 1875 **Retention of Basic Soldiering Skills** Joyce L. Shields, Stephen L. Goldberg, J. Douglas Dressel, 1979 Linear Multivariable Control Engineering Using GNU Octave

Wolfgang Borutzky, 2024-05-02 This textbook presents an in depth introductory survey of several fundamental advanced control concepts and techniques all ranging from modern ideas The book emphasizes ideas an understanding of key concepts methodologies and results In line with this the book addresses master's students in the overlap of engineering and computer science as well as engineers working in various application fields and interested in useful control techniques and less in system theories appealing from a mathematical point of view The book aims to show what methods and results learned for single variable systems are also applicable to multivariable systems what is different and why The structured text covers a broad spectrum of topics from decentralized control to the use of linear matrix inequalities LMIs Methods and results are illustrated by many examples and using free open source mathematical software predominately GNU Octave In some cases the free mathematical software package Scilab is also used The book features exercises and examples throughout

Novel Approaches for Studying Creativity in Problem-Solving and Artistic Performance Philip Fine, Amory H. Danek, Kathryn Friedlander, Ian Hocking, William Forde Thompson, 2020-01-31 **Cognitive Networks** Qusay Mahmoud, 2007-08-20

Cognitive networks can dynamically adapt their operational parameters in response to user needs or changing environmental conditions They can learn from these adaptations and exploit knowledge to make future decisions Cognitive networks are the future and they are needed simply because they enable users to focus on things other than configuring and managing networks Without cognitive networks the pervasive computing vision calls for every consumer to be a network technician The applications of cognitive networks enable the vision of pervasive computing seamless mobility ad hoc networks and dynamic spectrum allocation among others In detail the authors describe the main features of cognitive networks clearly indicating that cognitive network design can be applied to any type of network being fixed or wireless They explain why cognitive networks promise better protection against security attacks and network intruders and how such networks will benefit the service operator as well as the consumer Cognitive Networks Explores the state of the art in cognitive networks compiling a

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