

ROBOTICS AND AUTOMATION

UNIT 1 – BASIC CONCEPTS PART – A

1. Define a Robot? (Apr 2014)

RIA defines a robot as a “programmable, multifunction manipulator designed to Move materials, parts, tools or special devices through variable programmed motions for the performance of the variety of task”.

2. What is meant by automation and what are its types?

Automation is a technology that is concerned with the use of electronic mechanical and computer based system in the operation control and production.

Various types of automation:

- Fixed automation
- Programmable automation
- Flexible automation

3. Why a robot used?

- a. To reduce production cost
 - Fast
 - Accurate
 - Difficulties in human nature
- b. To avoid 3-D jobs
 - Dirty
 - Dangerous
 - Difficult

4. What is meant by robot anatomy?(Nov 2013)

Robot anatomy means study of structure of robot. Manipulator is constructed of a series of joints & links. A joint provides relative motion between the input link and the output link. Each joint provides the robot with one degree of freedom.

5. Write are the Benefits of industrial automation? (Apr 2014)

- Improved product quality
- Improved safety
- Increased manufacturing flexibility
- Improved operation reliability
- Improved decision making

6. Write Asimov's laws of robotics?(Nov 2013)

Three rules written by science fiction author Isaac Asimov and later expanded upon. These rules are built in to almost all positronic robots appearing in his fiction and cannot be bypassed. The rules are introduced in his 1942 short story Runaround although they were foreshadowed in a few earlier stories.

The Three Laws of Robotics are as follows:

- I. A robot may not injure a human being or, through inaction, allow a human being to come to harm.
- II. A robot must obey any orders given to it by human beings, except where such orders would conflict with the First Law.
- III. A robot must protect its own existence as long as such protection does not conflict with the First or Second Law.

7. Classify the motion control of Robot arm?

- Limited sequence control
- Point to point control
- Continuous path control
- Intelligent control

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Advances in Service and Industrial Robotics Karsten Berns, Daniel Görge, 2019-05-07 This book presents the proceedings of the 28th International Conference on Robotics in Alpine Danube Region RAAD 2019 held at the Fraunhofer Zentrum and the Technische Universität in Kaiserslautern Germany on 19-21 June 2019. The conference brought together academic

researchers in robotics from 20 countries mainly affiliated to the Alpe Adria Danube Region and covered all major areas of robotic research development and innovation as well as new applications and current trends Offering a comprehensive overview of the ongoing research in the field of robotics the book is a source of information and inspiration for researchers wanting to improve their work and gather new ideas for future developments It also provides researchers with an innovative and up to date perspective on the state of the art in this area **Advances in Manufacturing Technology XXXIII** Y.

Jin,M. Price,2019-08-22 The development and management of technologies and operations are key to the success of all types of manufacturing business This book presents the proceedings of the 17th International Conference on Manufacturing Research ICMR 2019 held in Belfast UK on 10 12 September 2019 ICMR has been the UK s main manufacturing research conference for 34 years and an international conference since 2003 It brings together researchers academics and industrialists to share their vision knowledge and experience and discuss emerging trends and new challenges in manufacturing research The conference theme of ICMR2019 was smart manufacturing and the book includes the 82 papers presented at the conference representing an acceptance rate of 69% These have been divided into 13 parts which cover topics ranging from robot automation and machining processes additive manufacturing composite manufacturing design methods to information management quality control production optimization and product lifecycle management Providing an overview of current trends and developments the book will be of interest to researchers and engineers in the relevant area of manufacturing processes design and production management **Mechatronics '98** J. Adolfsson,J. Karlsén,1998-08-28

Mechatronics a synergistic combination of mechanical electronic and computing engineering technologies is a truly multidisciplinary approach to engineering New products based on mechatronic principles are demonstrating reduced mechanical complexity increased performance and often previously impossible capabilities This book contains the papers presented at the UK Mechatronics Forum s 6th International Conference held in Skövde Sweden in September 1998 Many of these high quality papers illustrate the tremendous influence of mechatronics on such areas as manufacturing machinery automotive engineering textiles manufacture robotics and real time control and vision systems There are also papers describing developments in sensors actuators control and data processing techniques such as fuzzy logic and neural networks all of which have practical application to mechatronic systems **Multi-Agent Systems** Vadim Malvone, Aniello

Murano,2023-09-06 This volume LNCS 14282 constitutes the refereed proceedings of the 20th European Conference EUMAS 2023 held in Naples Italy during September 2023 This volume includes 24 full papers and 5 short papers carefully selected from 47 submissions Additionally the volume features 16 short papers rigorously reviewed from 20 submissions for the PhD day The conference focused on the theory and practice of autonomous agents and multi agent systems covering a wide range of topics **The Industrial Robot** ,1980 **Realising CIM's Industrial Potential** C. Kooij,P. MacConaill,J. Bastos,1993

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practitioners decision makers and researchers exchange experiences gained in developing and implementing CIM technologies This work deals with the application of technology innovation to industrial demand *Continual Improvement: A Bibliography with Indexes, 1992-1993*, 1994 **Robotics and Automation '84** International Association of Science and Technology for Development, 1984 Digital Human Modeling and Applications in Health, Safety, Ergonomics and Risk Management. Human Body Modeling and Ergonomics Vincent G. Duffy, 2013-06-28 This two volume set LNCS 8025 8026 constitutes the refereed proceedings of the Fourth International Conference on Digital Human Modeling and Applications in Health Safety Ergonomics and Risk Management formerly International Conference on Digital Human Modeling DHM 2013 held as part of the 15th International Conference on Human Computer Interaction HCII 2013 held in Las Vegas USA in July 2013 jointly with 12 other thematically similar conferences The total of 1666 papers and 303 posters presented at the HCII 2013 conferences was carefully reviewed and selected from 5210 submissions These papers address the latest research and development efforts and highlight the human aspects of design and use of computing systems The papers accepted for presentation thoroughly cover the entire field of Human Computer Interaction addressing major advances in knowledge and effective use of computers in a variety of application areas This two volume set contains 91 papers The papers in this volume focus on the following topics digital human modeling and ergonomics in working environments ergonomics of work with computers anthropometry posture and motion modeling **Industrial Robot Handbook** Richard K. Miller, 2013-11-21 These are exciting times for manufacturing engineers It has been said that American industry will undergo greater changes during the 1980 and 1990 decades than it did during the entire eight preceding decades of this century The industrial robot has become the symbol of this progress in computer integrated manufacturing This book is for engineers and managers in manufacturing industries who are involved in implementing robotics in their operations With tens of thousands of industrial robots already in use in the United States there are plenty of role models for proposed applications to be patterned after This book provides an overview of robot applications and presents case histories that might suggest applications to engineers and managers for implementation in their own facilities The application of industrial robots were well developed in the late 1970s and early 1980s While the reader may note some of the examples discussed in this handbook incorporate older robot models it is the application that is of interest As Joseph Engelberger the founding father of robotics has pointed out industrial robots in 1988 are doing pretty much the same kind of work as they did in 1980 Robot Technologies in Intralogistics. Possible Applications and Effects Ayse Akbulut, 2021-02-22 Seminar paper from the year 2018 in the subject Business economics Supply Production Logistics grade 1 0 University of Applied Sciences Dortmund language English abstract In the context of this term paper various robot solutions for the optimization of intra logistic processes shall be presented The objective is to present the possibilities of optimization by robot systems for logistical applications as well as to show the potentials and challenges of the intelligent systems In addition a comparison is made between the five main markets China Japan South

Korea USA and Germany to provide an overview of the world's advanced robot technology and to illustrate possible differences. The present work is divided into four chapters. The first chapter deals with the thematic introduction. In order to gain a sufficient understanding of intralogistics, the second chapter defines the terms intralogistics, robots, robotics, and cyber physical systems. The third chapter is devoted to the subject of robotics. After the detailed description of the structure of a robot system in the first subchapter of chapter three, the application areas for robots in intralogistics as well as their optimization possibilities are explained in the next subchapter. The following subchapter then compares both the positive and negative effects of robotic technologies. In order to gain a global overview of the differently advanced robot implementation, the five main markets are compared as well. Finally, a practical insight into the use of intelligent robot systems is presented, and a focus is put on possible trends and requirements for intra logistics. 4.0 The last chapter then concludes the topic. This chapter offers a brief forward-looking look into the future supported by literature. In addition, the current state of the art in the robotics segment is briefly described here, and a conclusion is then drawn.

Congressional Record United States. Congress, 1981. The Congressional Record is the official record of the proceedings and debates of the United States Congress. It is published daily when Congress is in session. The Congressional Record began publication in 1873. Debates for sessions prior to 1873 are recorded in The Debates and Proceedings in the Congress of the United States 1789-1824, the Register of Debates in Congress 1824-1837, and the Congressional Globe 1833-1873.

Resources in Education, 1995-07

Proceedings of the 2nd Conference on Industrial Robot Technology, University of Birmingham, U. K., March 27th-29th, 1974 ; Edited by T. E. Brock and Wendy A. Thornton University of Nottingham. Department of Production Engineering and Production Management, 1974

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